



LUNDS
UNIVERSITET

Nonlinear Control and Servo Systems

Lecture 2

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Today's Goal

To be able to

- *prove local and global stability of an equilibrium point through Lyapunov's method*
- *show stability of a set (for example, a limit cycle) through invariant set theorems*



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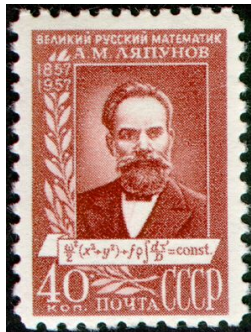


Material

- Slotine and Li: Chapter 3
- Lecture notes



Alexandr Mihailovich Lyapunov (1857–1918)



Master's thesis

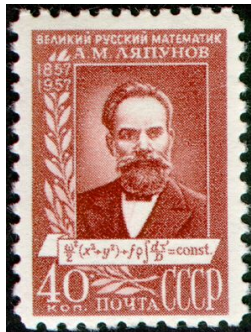
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Doctoral thesis

"The general problem of the stability of motion," 1892.



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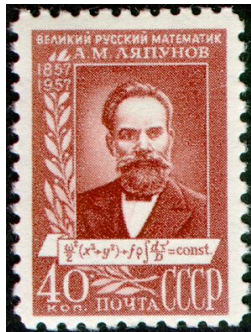
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Lyapunov's idea

If the total energy is dissipated, the system must be stable.

Main benefit

By looking at an energy-like function (a so called Lyapunov function), we might conclude that a system is stable or asymptotically stable **without solving** the nonlinear differential equation.

Main question

How to find a Lyapunov function?



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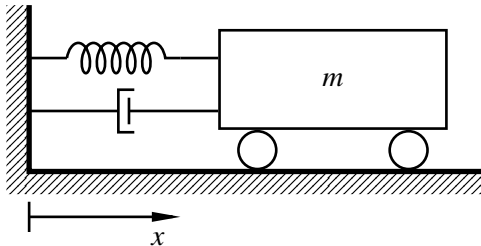
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A Motivating Example



$$m\ddot{x} = - \underbrace{b\dot{x}|\dot{x}|}_{\text{damping}} - \underbrace{k_0x - k_1x^3}_{\text{spring}}, \quad b, k_0, k_1 > 0$$

The energy can be shown to be

$$V(x, \dot{x}) = m\dot{x}^2/2 + k_0x^2/2 + k_1x^4/4 > 0, \quad V(0, 0) = 0$$
$$\frac{d}{dt}V(x, \dot{x}) = m\dot{x}\ddot{x} + k_0x\dot{x} + k_1x^3\dot{x} = -b|\dot{x}|^3 < 0, \quad \dot{x} \neq 0$$