Minimum Energy to send k bits with and without feedback

A nice result of Polyanskiy, Poor and Verdu (NEWS FLASH) + an attempt at improvement Bo Bernhardsson

A nice result of Polyanskiy, Poor and Verdu (NEWS FLASH) + an at Minimutatrifipeogyntese Bol Bentshariths and without feedback

Disclaimer

This is mainly presentation of work in

"Minimum energy to send k bits with and without feedback", Polyanskiy, Poor, Verdu, ISIT 2010, Austin, Texas, U.S.A., June 13 - 18, 2010

I have been fascinated by this paper for over a year, and talked with some of you about it

I will also show some results I obtained this morning while preparing this presentation.

And then I will show what I later found

Classical Asymptotic Results

Want to transmit information bits over a discrete time AWGN channel

 $y = x + z, \qquad z_k \sim N(0, N_0/2)$

Message of k bits coded into the possibly infinite sequence $x = (x_1, x_2, ...) \in \mathbb{R}^{\infty}$

Output sequence $y = (y_1, y_2, \ldots)$

Allowed block error probability ϵ

Energy measure $\sum x_k^2$

Shannon's Classical Result

Achievable Rate In the limit $\epsilon \to 0, k \to \infty$, the smallest achievable energy per bit $E_b = \frac{E}{k}$ is

$$\min \frac{E_b}{N_0} = \log_e 2 = -1.59 dB$$

where $N_0/2$ is the noise power per degree of freedom

Random block coding (with long blocks). Central limit theorem.

Fact: A noise-free (causal) feedback channel does not help, same performance!

What if a finite number of bits need to be transmitted?

(And what if we have a max delay constraint?)

Block code without feedback

An (E, M, ϵ) code is a list of code words

 $(c_1,\ldots,c_M)\in (\mathbb{R}^\infty)^M$

satisfying

$$||c_j||^2 \le E, \quad j=1,\ldots,M$$

and a decoder g satisfying

$$P[g(y) \neq W] \le \epsilon$$

where y is the response to $x = c_W$

Energy per bit if we send k bits

$$E_b(k,\epsilon) = rac{1}{k} \inf\{E: \exists (E,2^k,\epsilon) - ext{code}\}$$

Block Code with feedback

Similar to above, but where the encoder function has the form

$$X_k = f_k(W, Y_1^{k-1})$$

The encoder hence has (perfect) information about the past channel outputs

Energy restriction

$$E(\|x\|^2 \mid W = j) \le E, \quad \forall j$$

$$E_f(k,\epsilon) = rac{1}{k} \inf\{E: \exists (E,2^k,\epsilon) - ext{feedback code}\}$$

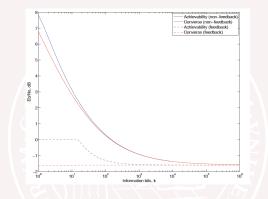
Results

Yury Polyanskiy, Vincent Poor, Sergio Verdu recently showed upper and lower bounds for the needed energy in the finite regime

Upper bounds: A coder and decoder is found giving a certain performance

Lower bounds: Information theory is used to prove that you can't do better

Finite Block Length Performance



Huge improvement by feedback for finite block lengths !

Open question: Is the lower red line achievable with feedback?

Can one transmit one bit of information over the AWGN channel using energy = ln(2) = -1.59dB ??

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Notation

Area to the right of x of a Gaussian normal distribution

$$Q(x) = \int_{x}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-t^{2}/2} dt = \operatorname{Prob}(Z_{n} > x)$$

No Feedback - Upper and Lower Bound

There exists an $(E, 2^k, \epsilon)$ code with

$$\epsilon = 1 - rac{1}{\sqrt{\pi N_0}} \int_{-\infty}^\infty \left[1 - Q\left(rac{z}{\sqrt{N_0/2}}
ight)
ight]^{2^k - 1} e^{-rac{(z - \sqrt{E})^2}{N_0}} dz$$

Proof: Use $x = \sqrt{E}e_i$ and ML-decoder $i = \operatorname{argmax}_i y_i$

Any $(E, 2^k, \epsilon)$ code without feedback satisfies

$$rac{1}{2^k} \geq Q\left(\sqrt{rac{2E}{N_0}} + Q^{-1}(1-\epsilon)
ight)$$

Proof: More difficult, but not extremly hard

Feedback - Lower Bound

Shannon's asymptotic result for $k \to \infty, \epsilon \to 0$

$$\frac{E_b}{N_0} \ge \ln(2) = -1.59 \text{ dB}$$

is obviusly a valid bound for all finite k as well.

If error probability $\epsilon > 0$ is allowed one can instead prove the slightly weaker lower bound

$$\frac{E_b}{N_0} \ge \ln(2)d(1-\epsilon\|2^{-k})$$

where $d(x||y) = x \log \frac{x}{y} + (1-x) \log \frac{1-x}{1-y}$ is the binary relative entropy

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Feedback - Upper Bound

How should one construct a feedback scheme that improves decoding?

Idea: Use more transmit energy if the decoder is on the wrong track

Consider the case with k = 1 bit of information to be transmitted

The following scheme achieves error-free transmission with

$$\frac{E}{N_0} = 1 = 0 \text{ dB}$$

using an ML-decoder:

Transmitting one bit of information with $E = N_0$

Assume $W = \pm 1$ and choose an arbitrary constant d > 0

At time *n* transmit

$$x_n = \begin{cases} Wd & P(W \mid Y_1^{n-1}) \le P(-W \mid Y_1^{n-1}) \\ 0 & \text{otherwise} \end{cases}$$

If W=1 we will hence use $x_n = u$ if the ML-decoder is on the wrong track, else $x_n = 0$

Why does the scheme give $\epsilon = 0$ and expected energy $E = N_0$?

Sketch of Proof

Log-likelihood ratio

$$S_n = \log \frac{P(W = +1 \mid Y^n)}{P(W = -1 \mid Y^n)}$$

For $W = \pm 1$

$$S_n = S_{n-1} + dZ_n \pm \frac{1}{2}d^2$$
 (exercise)

When $u \rightarrow 0$, S_n hence behaves like a random-walk with a positive or negative trend

With B_t Brownian motion we have

$$S_n = \left(rac{t}{2} + \sqrt{rac{N_0}{2}}B_t
ight)_{t=nd^2}$$

Random walk with positive trend if W = 1, negative if W = -1

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Analysis

Amount of energy spent = Average time S_n is spent below zero

$$\begin{split} E(T) &= \int_0^\infty P\left(\frac{t}{2} + \sqrt{\frac{N_0}{2}}B_t \le 0\right) dt = \\ &= \int_{t=0}^\infty Q(\frac{t/2}{\sqrt{N_0 t/2}}) dt \\ &= \int \int_{0 \le t \le 2x^2 N_0} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx dt \\ &= \frac{1}{\sqrt{2\pi}} \int_{x=0}^\infty 2x^2 N_0 e^{-x^2/2} dx = N_0 \end{split}$$

A similar scheme give another upper bound (see figure) when k > 1

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Open Questions

To beat this performance, one should come up with a more clever feedback scheme.

- Can you find a feedback scheme that achieves the magical -1.59dB energy to transmit a single bit?
- What if the feedback channel has limited capacity?
- What if we have finite time available and decoding must be achieved before a certain deadline?

News Flash

PPV uses a relay controller of the log-likelihood ratio S

$$u_1(S) = d \, 1_{S \le 0}$$
 and $u_{-1}(S) = -u_1(-S)$

The only thing used in the proof is really that

$$u_1(S) + u_1(-S) = d$$
 and $u_{-1}(S) = -u_1(-S)$ (1)

Proof: If W = 1 we get (for $N_0 = 1$)

$$S_n - S_{n-1} = -\frac{1}{2} \left[(Y_n - u_1(S))^2 - (Y_n - u_{-1}(S))^2 \right]$$

[Use $Y_n = u_1(S) + Z_n$ and (1)]
$$= -\frac{1}{2} \left[Z_n^2 - (d + Z_n)^2 \right]$$

$$= dZ_n + \frac{d^2}{2}$$

Same as before! We can optimize over all $u_1(S)$ fullfilling (1)

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BoB's Optimization

We want to find u(S) that minimizes the spent energy If $N_0 = 1$ it is given by

$$E = \int_{t=0}^{\infty} \int_{x=-\infty}^{\infty} u^2(x) \frac{1}{\sqrt{\pi t}} e^{-\frac{(x-t/2)^2}{t}} dx dt$$

= $\int_{x=0}^{\infty} u^2(x) f(x) + (1-u(x))^2 f(-x) dx$

where

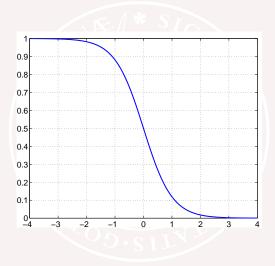
$$f(x) = \int_{t=0}^{\infty} \frac{1}{\sqrt{\pi t}} e^{-\frac{(x-t/2)^2}{t}} dt = 2\min(e^{2x}, 1)$$

The optimal controller is given by

$$u(x) = \frac{f(-x)}{f(x) + f(-x)} = \frac{e^{-x}}{e^x + e^{-x}}$$

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Optimal Controller



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Resulting Optimized Performance

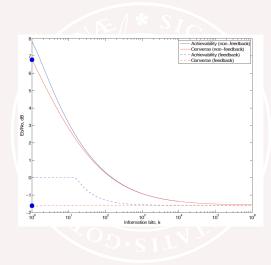
With this u(x) we get the energy

$$E = \int_{x=-\infty}^{\infty} u^2(x) 2\min(e^{2x}, 1) dx$$

= $\int_{x=-\infty}^{0} \left(\frac{e^{-x}}{e^x + e^{-x}}\right)^2 2e^{2x} dx + \int_{x=0}^{\infty} \left(\frac{e^{-x}}{e^x + e^{-x}}\right)^2 2dx$
= $\ln(2)$

This means we have closed the gap between the upper and lower bound and solved the outstanding open question in PPV!

Optimal Controller



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News Flash 2

While looking for the address to one of the authors, after finding this nice result, I found a link to a new journal publication I was not aware of:

Y. Polyanskiy, H. V. Poor and S. Verdú, "Minimum energy to send k bits through the Gaussian channel with and without feedback," IEEE Trans. Inf. Theory, vol. 57, no. 8, pp. 4880 - 4902, Aug. 2011, **submitted May 5 2011**.

This article contains the result I just sketched :-(

Conclusions

- Feedback improves performance for finite block length making the Shannon asymptotic AWGN performance even for a block of one bit
- Many interesting problems with imperfect feedback channel and/or delay constraints are still open
- Always check the recent literature
- Do not postpone giving internal seminars